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SYSTEMS

# TELEREMOTE ASSIST



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## TELEREMOTE ASSIST



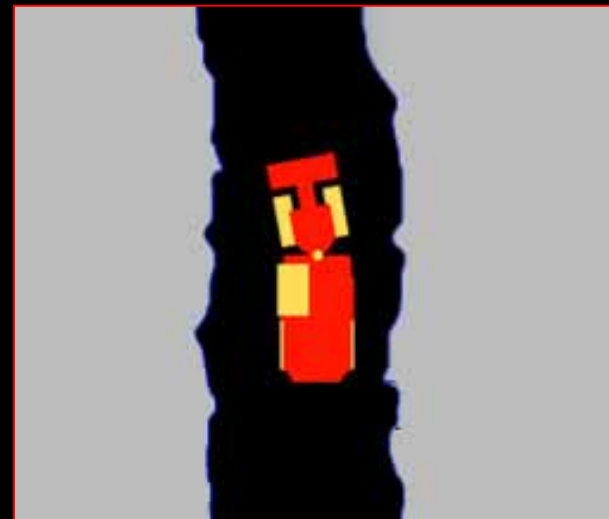
The **Control Master®** Teleremote Assist is a visual aid that has been designed to assist the remote machine operator to avoid damaging machines in an underground mining environment. It provides a Real Time image of the machine, its articulation angle and the position of the walls relative to the machine with centimetre accuracy.

The Teleremote Assist integrates seamlessly with existing **Control Master®** installations utilising the existing Teleremote communications network. This also means that no additional infrastructure is required and maintenance is minimised.

The image provided by Teleremote Assist provides the operator with a Real Time overhead view of the machine and its surroundings. This takes the guess work out of driving a Teleremote machine as the operator can see exact distances, not a flat camera view. When integrated with the **Control Master®** Teleremote system, the operator can utilise both a camera view and an above the machine plan view allowing greater productivity with less damage to the machine.

### BENEFITS

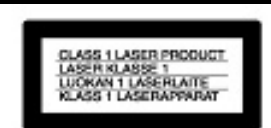
- Reduces machine damage
- Prolongs machine life
- Low maintenance
- Uses existing communication system
- Improves productivity of Teleremote controlled machines, even in dusty work areas
- Assists align machine during Teleremote operation





## Component 1: Lasers

- ❑ Mounted forward and reverse of articulation point.
- ❑ Continuous distance is measured between laser and wall.
- ❑ Lasers are mounted in the same position as existing camera mounts from the **Control Master®** Teleremote system.





## Component 2: Angle Sensor

- ❑ Allows the system to calculate the geometry of the environment.
- ❑ Accurately represents the machine's shape and position.
- ❑ Positioned at the machine's articulation point.
- ❑ Protected from environmental damage.



Angle Sensor

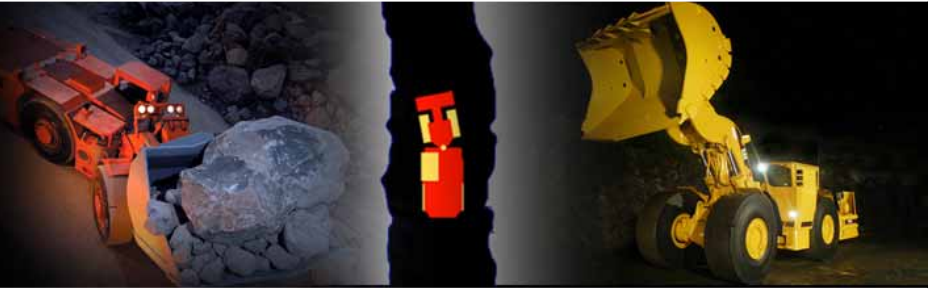




### Component 3 & 4: Processing unit & camera distribution unit

- ❑ Processing Unit: This unit takes the information from both the lasers and the angle sensor to generate the final image that is presented to the operator.
- ❑ Camera Distribution Unit: This unit along with a toggle activates the forward, rear and third camera view.





## Operation:

- ❑ Three screens, one showing the image generated and the other two shows front and rear vision of the machine with the option of a third camera.
- ❑ Graphical representation of the machine, articulation angle and the environment that it is in.
- ❑ Operator sees a scale representation of the machine they are driving and the wall around the machine (centimetre accuracy).
- ❑ Operator is able to see precisely the distance of the machine from the walls in Real Time.
- ❑ The Teleremote Assist can be relied upon if the vision is obstructed by a dusty environment through the cameras on the Teleremote system.

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**Personnel Carrier Option:**







**Thank you for your attention**

**We look forward to working with you & your team  
to make mining safer & more productive**

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